

APPLICATION OF MEASURE OF NONCOMPACTNESS TO VOLTERRA EQUATIONS OF CONVOLUTION TYPE

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ABSTRACT. Sufficient conditions for the existence of at least one solution of a nonlinear integral equation with a general kernel are established. The existence result is proved in $C([0, T], E)$, where E denotes an arbitrary Banach space. We use Darbo-Sadovskii fixed point theorem and techniques of measure of noncompactness. We extend and generalize results obtained by other authors in the context of fractional differential equations. One example illustrates the theoretical results.

1. Introduction. During the past years the theory of functional Volterra integral equations have undergone rapid development. The growth has been strongly promoted by the large number of applications that this theory has found in rheology, risk theory, renewal theory, branching processes, queuing theory, and inventory analysis [12]. Recent developments include studies on state dependent delay [16], perturbations [13] and attractive behaviour of solutions [6], [7].

In this paper we study existence of solutions for the following nonlinear Volterra integral equation of convolution type

$$(1.1) \quad u(t) = \int_0^t a(t-s)f(s, u(s)) ds \quad t \in [0, T],$$

where $a \in L^1_{loc}(\mathbb{R}_+)$ is a scalar kernel, E is a Banach space with the norm $\|\cdot\|$ and $f : [0, T] \times E \rightarrow E$ satisfies some suitable conditions.

Equation (1.1) was studied by A. Aghajani, E. Pourhadi and J.J. Trujillo in [3] for the case $a(t) = \frac{t^{\alpha-1}}{\Gamma(\alpha)}$ and $0 < \alpha < 1$. See [3, Lemma 3.1] and [21] where the precise notion of solution is defined. They investigate the existence of solutions for the associated Cauchy problem using a nice generalization of Darbo's fixed point theorem via the Hausdorff measure of noncompactness and give interesting concrete examples.

The technique of measure of noncompactness to solve evolution equations has been used increasingly in the last time due to their efficiency when compared with other methods. For instance, Banaś and Nalepa in [8] showed that with help of that measure of noncompactness, one can obtain an existence result for a nonlinear quadratic integral equation of Hammerstein type in Hölder spaces. Existence results for impulsive differential equations with nonlocal conditions via measures of noncompactness has been proved by Mallika Arjunan, Kavitha and Selvi [18]. Also, Allahyari, Arab and Shole Haghighi in [5] studied the existence of solutions for some classes of integro-differential equations. However this study does not include the convolution type equation (1.1). Nonlinear functional equations of convolution type on the line and with external force term has been studied in Lebesgue spaces by Khosravi, Allahyari and Shole Haghighi in the recent reference [15]. On the other hand, application of measure of noncompactness to ℓ_1 -solvability of infinite systems of second order differential equations has been considered by Aghajani and Pourhadi in [2], and by M. Mursaleen and S.M.H. Rizvi in [19]. Also, the authors in [20] studied an application of measure of noncompactness to ℓ_p -solvability of infinite systems of differential equations. For an up to date account of this method and its applications see also the recent monograph by Banaś and Mursaleen [10].

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Since fractional differential equations are particular cases of functional integral equations of the type (1.1) it is natural to ask for the following problem:

(Q) For which class of kernels $a(t)$ there exist solutions for (1.1)?

We remark that this is an inverse problem in terms of the kernel $a(t)$ and therefore it is not included in the recent reference [14] where existence of solutions for a very general class of integral equations was studied.

We have success to solve problem (Q) for the class of kernels $a(t)$ that satisfy the following condition: There exists $0 < \sigma < 1$ such that $a \in L^{\frac{1}{\sigma}}([0, T]; \mathbb{R})$ and

$$(1.2) \quad \lim_{h \rightarrow 0} \int_0^T |a(s+h) - a(s)|^{\frac{1}{1-\sigma}} ds = 0,$$

holds.

It is interesting to note that the class of kernels defined by $a(t) = e^{-\delta t}$ satisfy our assumptions under some mild restrictions on the parameter $\delta > 0$. This class of kernels naturally appears in the theory of integral equations of convolution type. They corresponds to Maxwell type materials in viscoelasticity theory (relaxation modulus). See [17, Chapter 2, Section 2.4]. A concrete example is provided in the last section of this paper.

In order to obtain our results, we use the properties of measure of noncompactness and a consequence of Darbo-Sadovskii fixed point theorem (see [1, 2]) to prove the existence of solutions of the Equation (1.1) under the hypothesis that the nonlinearity $f(t, u)$ satisfies the Carathéodory type condition and it is dominated by a control function which is radial with respect to u .

The outline of this paper is as follows: Section 2 is devoted to preliminaries, recalling the definition and fundamental properties of measure of noncompactness, mentioning a generalization of Darbo fixed point theorem due to Aghajani, Banaś and Sabzali [1, Theorem 2.2], and recalling Bothe's Lemma (see [11]) which is the essential ingredient in the proof of our main result.

Section 3 shows the existence of at least one solution of (1.1) on an arbitrary Banach space E by using arguments of measure of noncompactness, a consequence of Darbo-Sadovskii fixed point theorem and, again, certain hypothesis on the kernel and the function f .

In Section 5, we give a concrete example of our main result considering as external nonlinear force

$$f(t, x) = \frac{1}{t^2 + \frac{1}{2}} \left(\ln(|x_k| + 1) + \frac{t}{k^2} \right)_{k=1}^{\infty}$$

for every $x = (x_k) \in c_0$, where c_0 is the Banach space of null sequences which consists of all sequences whose limit is zero; as well as the Maxwell type materials present in the kernel $a(t) = e^{-\delta t}$.

Finally, it is interesting to observe that for this function f the existence of at least one solution on c_0 is ensured under the hypothesis $0 < \delta < 2$ and $0 < T < \frac{1}{2}$.

2. Preliminaries. Suppose that $(E, \|\cdot\|)$ is a Banach space and denote by $C([0, T], E)$ the space of all continuous functions equipped with the norm

$$\|u\|_{\infty} = \sup_{s \in [0, T]} \|u(s)\|.$$

Let $L^1([0, T]; E)$ be the space of all Bochner integrable functions $h : [0, T] \rightarrow E$ endowed with the norm

$$\|h\|_{L^1([0, T]; E)} = \int_0^T \|h(s)\|_E ds.$$

Now, we mention some results and facts about measure of noncompactness.

We denote by \overline{X} and $\text{Conv } X$ the closure and the convex closure of X as a subset of E , respectively. Further, we denote by \mathfrak{M}_E the family of all nonempty bounded subsets of E and \mathfrak{R}_E its subfamily consisting of all relatively compact sets.

We recall that the Hausdorff of measure of noncompactness γ defined on a bounded set M of a Banach space E is given by

$$\gamma(B) = \inf\{\epsilon > 0 : B \text{ has a finite cover by balls of radius } \epsilon\}.$$

Definition 2.1 ([9]). *A mapping $\gamma : \mathfrak{M}_E \rightarrow \mathbb{R}^+$ is said to be a measure of noncompactness in E if satisfies the following conditions:*

- (a) *The family $\ker \gamma = \{X \in \mathfrak{M}_E : \gamma(X) = 0\}$ is nonempty and $\ker \gamma \subset \mathfrak{R}_E$.*
- (b) *$X \subset Y$ implies $\gamma(X) \leq \gamma(Y)$.*
- (c) *$\gamma(\overline{X}) = \gamma(X)$.*
- (d) *$\gamma(\text{Conv}(X)) = \gamma(X)$.*
- (e) *$\gamma(X \cup Y) = \max\{\gamma(X), \gamma(Y)\}$.*
- (f) *$\gamma(rX) = |r|\gamma(X)$ for any $r \in \mathbb{R}$.*
- (g) *$\gamma(X + Y) \leq \gamma(X) + \gamma(Y)$.*
- (h) *If the mapping $T : D(T) \subset E \rightarrow F$ is Lipschitz continuous with constant k , then $\gamma_F(TB) \leq k\gamma_E(B)$ for any bounded set $B \subset D(T)$, where F is a Banach space and γ_A denotes the measure of noncompactness corresponding to a Banach space A .*
- (i) *For all $\lambda \in [0, 1]$,*

$$\gamma(\lambda X + (1 - \lambda)Y) \leq \lambda\gamma(X) + (1 - \lambda)\gamma(Y).$$

- (j) *If $(X_n)_{n \in \mathbb{N}}$ is a sequence of closed sets from \mathfrak{M}_E such that*

$$X_{n+1} \subset X_n \text{ for all } n = 1, 2, 3, \dots \text{ and } \lim_{n \rightarrow \infty} \gamma(X_n) = 0,$$

then

$$X_\infty = \bigcap_{n=1}^{\infty} X_n \neq \emptyset.$$

The family $\ker \gamma$ described in (a) is said to be the kernel of the measure of noncompactness γ .

Let $I := [0, T]$. We need the following results.

Lemma 2.2 ([9]). *If $W \subset C(I, E)$ is bounded and equicontinuous, then the set $\gamma(W(t))$ is continuous on I and*

$$\gamma(W) = \sup_{t \in I} \gamma(W(t)), \quad \gamma\left(\int_0^t W(s) ds\right) \leq \int_0^t \gamma(W(s)) ds.$$

Lemma 2.3 ([11]). *If $(u_n)_{n \in \mathbb{N}} \subset L^1(I; E)$ satisfies $\|u_n\| \leq \kappa(t)$ a.e. on I for all $n \geq 1$ and for some $\kappa \in L^1(I; (0, \infty))$, then the function $\gamma((u_n(t))_{n \in \mathbb{N}})$ belongs to $L^1(I; (0, \infty))$ and*

$$(2.1) \quad \gamma\left(\left\{\int_0^t u_n(s) ds : n \geq 1\right\}\right) \leq 2 \int_0^t \gamma(\{u_n(s) : n \geq 1\}) ds.$$

The following result will be the key tool in the proof of our main result.

Lemma 2.4 ([11]). *If $W \subset C(I, E)$ is bounded, then for each $\epsilon > 0$, there exists a sequence $(u_n)_{n \in \mathbb{N}} \subset W$ such that*

$$(2.2) \quad \gamma(W) \leq 2\gamma((u_n)_{n \in \mathbb{N}}) + \epsilon.$$

To prove our main result, we need the following theorem due to Aghajani, Banás and Sabzali [1, Theorem 2.2] which is a generalization of the Darbo's fixed point.

Theorem 2.5. [1, Theorem 2.2] *Let C be a nonempty, bounded, closed, and convex subset of a Banach space E and let $T : C \rightarrow C$ be a continuous function satisfying*

$$\gamma(T(W)) \leq \phi(\gamma(W))$$

for each $W \subset C$, where γ is an arbitrary measure of noncompactness and $\phi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ is a monotone increasing (not necessarily continuous) function with

$$\lim_{n \rightarrow \infty} \phi^n(t) = 0 \quad \text{for all } t \geq 0.$$

Then T has at least one fixed point in C .

3. Existence of solutions.

In this section we investigate solutions of the problem

$$(3.1) \quad u(t) = \int_0^t a(t-s)f(s, u(s)) ds \quad t \in [0, T],$$

where $a \in L^1_{loc}(\mathbb{R}_+)$ is a scalar kernel, E is a Banach space with the norm $\|\cdot\|$ and $f : [0, T] \times E \rightarrow E$ satisfies some suitable conditions.

We need the following assumptions

(H1) f satisfies Carathéodory type conditions; i.e., $f(\cdot, x)$ is measurable for each x and $f(t, \cdot)$ is continuous for a.e. $t \in I$.

(H2) For any $0 < q < 1$ there exists a function $m \in L^{\frac{1}{\beta}}(I; \mathbb{R}^+)$ where $0 < \beta < q$ and a nondecreasing continuous function $\Phi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ such that

$$\|f(t, x)\| \leq m(t)\Phi(\|x\|)$$

for all $x \in E$ and almost all $t \in I$.

(H3) There exists a function $H \in L^1(I; \mathbb{R}^+)$ such that for any bounded $B \subseteq X$

$$\gamma(f(t, B)) \leq H(t)\phi(\gamma(B))$$

for almost all $t \in I$. (Here ϕ is some function that satisfies the same conditions of the Theorem 2.5).

(H4) $a \in L^{\frac{1}{\beta}}(I; \mathbb{R})$ and satisfies

$$(3.2) \quad \lim_{h \rightarrow 0} \int_0^T |a(\tau+h) - a(\tau)|^{\frac{1}{1-\beta}} d\tau = 0.$$

(H5) There exist at least one solution $p \in C(I, (0, \infty))$ to the inequality

$$(3.3) \quad \Phi(\|p\|_0) \int_0^t a(t-s)m(s) ds \leq p(t), \quad t \in I,$$

where $\|\cdot\|_0$ is the sup norm in $C(I, (0, \infty))$.

The next theorem is the main result of this paper.

Theorem 3.1. *Suppose that the hypothesis (H1)-(H5) hold. Then the Problem (3.1) has at least one solution $u \in C(I, E)$.*

Proof. Let $\mathcal{F} : C(I, E) \rightarrow C(I, E)$ be defined by

$$(\mathcal{F}u)(t) := \int_0^t a(t-s)f(s, u(s)) ds, \quad t \in I,$$

for all $u \in C(I, E)$. Let $p(t)$ be the function which satisfies (H5) and $p_0 = \inf_{t \in I} p(t) > 0$. We define

$$B_p := \{u \in C(I, E) : \|u\|_E \leq p_0\}.$$

Set

$$C_p := \text{Conv } \mathcal{F}B_p.$$

We proceed to verify the hypothesis of Theorem 2.5 dividing the proof in five steps.

Step 1. Conv $\mathcal{F}B_p$ is equicontinuous.

It is enough to prove that $\mathcal{F}B_p$ is equicontinuous because the concepts of boundedness and equicontinuity have hereditary properties related to the closure of the convex hull in $C(I, E)$.

Indeed, let $u \in B_p$ and $0 \leq t_1 < t_2 \leq T$ be given. Then

$$\begin{aligned} \|\mathcal{F}(u)(t_2) - \mathcal{F}(u)(t_1)\| &\leq \left\| \int_0^{t_2} a(t_2-s)f(s, u(s)) ds - \int_0^{t_1} a(t_1-s)f(s, u(s)) ds \right\| \\ &\leq \int_0^{t_1} |a(t_2-s) - a(t_1-s)| \|f(s, u(s))\| ds \\ &\quad + \int_{t_1}^{t_2} |a(t_2-s)| \|f(s, u(s))\| ds \\ &\leq \int_0^{t_1} |a(t_2-s) - a(t_1-s)| m(s) \Phi(\|u(s)\|) ds \\ &\quad + \int_{t_1}^{t_2} |a(t_2-s)| m(s) \Phi(\|u(s)\|) ds \\ &\leq \int_0^{t_1} |a(t_2-s) - a(t_1-s)| m(s) \Phi(\|p(s)\|) ds \\ &\quad + \int_{t_1}^{t_2} |a(t_2-s)| m(s) \Phi(\|p(s)\|) ds \\ &\leq \Phi(\|p\|_0) \left(\int_0^{t_1} |a(t_2-s) - a(t_1-s)| m(s) ds + \int_{t_1}^{t_2} |a(t_2-s)| m(s) ds \right). \end{aligned}$$

It follows from Hölder inequality and (H4) that

$$\begin{aligned} \|\mathcal{F}(u)(t_2) - \mathcal{F}(u)(t_1)\| &\leq \Phi(\|p\|_0) \|m\|_{L^{\frac{1}{\beta}}(I, (0, \infty))} \\ &\quad \times \left[\left(\int_0^T |a((t_2-t_1) + \tau) - a(\tau)|^{\frac{1}{1-\beta}} d\tau \right)^{1-\beta} \right. \\ &\quad \left. + \left(\int_0^{t_2-t_1} |a(s)|^{\frac{1}{\beta}} ds \right)^\beta \right] \rightarrow 0 \quad \text{as } t_1 \rightarrow t_2. \end{aligned}$$

Step 2. \mathcal{F} is continuous on $C(I, E)$.

Since f satisfies the conditions (H1) and (H2) then \mathcal{F} is well-defined (consequence of Young's inequality).

Let (u_n) be a sequence of functions in $C(I, E)$ which converges to $u \in C(I, E)$. We have to prove that $\|\mathcal{F}u_n - \mathcal{F}u\|_\infty \rightarrow 0$ as $n \rightarrow \infty$. Since $f(t, \cdot)$ is continuous, then $\|f(s, u_n(s)) - f(s, u(s))\| \rightarrow 0$ as $n \rightarrow \infty$. On the other hand, it follows from condition (H2) that

$$\|f(s, u_n(s)) - f(s, u(s))\| \leq 2m(s) \left[\Phi(\|u_n(s)\|) + \Phi(\|u(s)\|) \right].$$

By (H2) and (H4) we have that $a(t)$ and $m(t)$ are integrable. Therefore, the inequality

$$\begin{aligned} \int_0^t |a(t-s)| |m(s)| \Phi(\|u(s)\|) ds &\leq \int_0^t |a(t-s)| |m(s)| \Phi(\|u\|_\infty) ds \\ &= \Phi(\|u\|_\infty) \int_0^t |a(t-s)| |m(s)| ds, \end{aligned}$$

yields that $s \mapsto a(t-s)m(s)\Phi(\|u(s)\|)$ is also Lebesgue integrable on $[0, T]$. By Dominated Convergence Theorem we obtain

$$\|(\mathcal{F}u_n)(t) - (\mathcal{F}u)(t)\| \leq \int_0^t |a(t-s)| \|f(s, u_n(s)) - f(s, u(s))\| ds \rightarrow 0 \quad \text{as } n \rightarrow \infty$$

for all $t \in I$. Hence $\|\mathcal{F}u_n - \mathcal{F}u\|_\infty \rightarrow 0$ on I as $n \rightarrow \infty$. We conclude that \mathcal{F} is continuous on $C(I, E)$.

Step 3. \mathcal{F} is bounded from B_p into itself.

Let $u \in B_p$ and $t \in I$. Using (H2) and (H5) we get

$$\begin{aligned} \|\mathcal{F}u(t)\| &\leq \int_0^t |a(t-s)| \|f(s, u(s))\| ds \leq \int_0^t |a(t-s)m(s)\Phi(\|u(s)\|) ds \\ &\leq \int_0^t |a(t-s)m(s)\Phi(\|p(s)\|) ds \leq \Phi(\|p\|_0) \int_0^t |a(t-s)m(s) ds \leq p(t) \quad (t \in I). \end{aligned}$$

The conclusion follows. This step also prove that $\mathcal{F}(B_p) \subset B_p$.

Step 4. $\mathcal{F} : C_p \rightarrow C_p$ is well-defined and is continuous.

Note that $B_p \subset C(I, E)$ is bounded, closed and convex. Since $\mathcal{F}(B_p) \subset B_p$ by preceding step and from the fact that B_p is convex, we obtain

$$C_p = \text{Conv } \mathcal{F}B_p \subset \text{Conv } B_p = B_p.$$

Since the convex hull of a subset is the smallest convex set that contains to the subset, we have that

$$\mathcal{F}C_p \subset \mathcal{F}B_p \subset \text{Conv } \mathcal{F}B_p = C_p.$$

This shows that $\mathcal{F} : C_p \rightarrow C_p$ is well-defined. From step 2 we have that \mathcal{F} is continuous on C_p .

Step 5.

Let $C \subset C_p$ be arbitrary. By step 4 we have that C is bounded. From Lemma 2.4 we infer that given $\epsilon > 0$, there exists a sequence $(u_n)_{n \in \mathbb{N}} \subset C$ such that

$$\begin{aligned} \gamma(\mathcal{F}C)(t) &= \gamma \left(\left\{ \int_0^t a(t-s)f(s, u(s)) ds : u \in C \right\} \right) \\ &\leq 2\gamma \left(\left\{ \int_0^t a(t-s)f \left(s, (u_n(s))_{n \in \mathbb{N}} \right) ds : u \in C \right\} \right) + \epsilon. \end{aligned}$$

Next, Lemma 2.2 and Lemma 2.3 together with condition (H3) imply

$$\begin{aligned} \gamma(\mathcal{F}C)(t) &\leq 4 \int_0^t a(t-s) \gamma\left(\{f(s, u_n(s)) : n \in \mathbb{N}\}\right) ds + \epsilon \\ &\leq 4 \int_0^t a(t-s) H(s) \gamma\left(\phi(\gamma((u_n)_{n \in \mathbb{N}}))\right) ds + \epsilon \\ &\leq 4\phi(\gamma((u_n)_{n \in \mathbb{N}})) \int_0^t a(t-s) H(s) ds + \epsilon \\ &\leq 4\phi(\gamma((u_n)_{n \in \mathbb{N}})) \int_0^T a(t-s) H(s) ds + \epsilon \leq 4\phi(\gamma(C))(a * H)(T) + \epsilon, \end{aligned}$$

where we have used in the last inequality that ϕ is increasing and the fact of $(a * H)(t)$ is well-defined. Since $\epsilon > 0$ was arbitrary, we have

$$(3.4) \quad \gamma(\mathcal{F}C)(t) \leq 4(a * H)(T)\phi(\gamma(C)).$$

Let

$$\psi(s) = 4(a * H)(T)\phi(s).$$

It follows from the properties of ϕ that $\psi : [0, \infty) \rightarrow [0, \infty)$ is monotone increasing, $\lim_{n \rightarrow \infty} \psi^n(t) = 0$ for all $t \geq 0$. Also, by (3.4) we obtain that $\gamma(\mathcal{F}C)(t) \leq \psi(\gamma(C))$.

We have proved that $\mathcal{F} : C_p \rightarrow C_p$ is a continuous function satisfying

$$\gamma(\mathcal{F}C)(t) \leq \psi(\gamma(C))$$

for each $C \subset C_p$, where γ is a measure of noncompactness and $\psi : [0, \infty) \rightarrow [0, \infty)$ is a monotone increasing function with $\lim_{n \rightarrow \infty} \psi^n(t) = 0$ for all $t \geq 0$. It follows from Theorem 2.5 that \mathcal{F} has at least one fixed point $u \in C_p \subset C(I, E)$. \square

Remark 3.2. We observe that condition (H4) fails in case of $a(s) = s^q$ for $q < -\beta$.

As a particular case, we recover the main result on existence of solutions to the Cauchy problem for the fractional difference equation $D_t^\alpha u(t) = f(t, u(t))$, $0 < \alpha < 1$ established by Aghajani, Pourhadi and Trujillo in [3, Theorem 3.1].

Theorem 3.3. Consider the equation

$$(3.5) \quad u(t) = \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} f(s, u(s)) ds \quad t \in [0, T],$$

where $q \in (0, 1)$, E is a Banach space with the norm $\|\cdot\|$ and $f : [0, T] \times E \rightarrow E$ satisfies the conditions (H1), (H3) and

(H2)' There exists a function $m \in L^{\frac{1}{\beta}}(I; \mathbb{R}^+)$ where $0 < \beta < q$ and a nondecreasing continuous function $\Phi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ such that

$$\|f(t, x)\| \leq m(t)\Phi(\|x\|)$$

for all $x \in E$ and almost all $t \in I$.

(H5)' There exist at least one solution $p \in C(I, (0, \infty))$ to the inequality

$$(3.6) \quad \frac{\Phi(\|p\|_0)}{\Gamma(q)} \int_0^t (t-s)^{q-1} m(s) ds \leq p(t), \quad t \in I,$$

where $\|\cdot\|_0$ is the sup norm in $C(I, (0, \infty))$.

Then the Equation (3.5) has at least one solution $u \in C(I, E)$.

Proof. Let $a(t) = \frac{t^{q-1}}{\Gamma(q)}$ in Theorem 3.1. From (H2)' we have $0 < \beta < q < 1$ for some β . It follows that

$$\begin{aligned} \frac{1}{\Gamma(q)^{\frac{1}{1-\beta}}} \int_0^t [(\tau+h)^{q-1} - \tau^{q-1}]^{1/1-\beta} d\tau &\leq \frac{1}{\Gamma(q)^{\frac{1}{1-\beta}}} \int_0^t [(\tau+h)^{\frac{q-1}{1-\beta}} - \tau^{\frac{q-1}{1-\beta}}] d\tau \\ &= \frac{1}{\Gamma(q)^{\frac{1}{1-\beta}}} \frac{1-\beta}{q-\beta} \left[(t+h)^{\frac{q-\beta}{1-\beta}} - h^{\frac{q-\beta}{1-\beta}} - t^{\frac{q-\beta}{1-\beta}} \right] \rightarrow 0, \end{aligned}$$

as $h \rightarrow 0$, where we have used the inequality $(a-b)^r \leq a^r - b^r$, $a > b > 0, r > 0$. This shows (H3).

On the hand, note that (H5) is a direct consequence of (H5)'. The conclusion follows from Theorem 3.1. □

Remark 3.4. Note that the Hausdorff measure of noncompactness of the unit ball in finite dimensional $E = \mathbb{R}^n$ is zero. It follows that the condition (H3) is redundant. Thus we obtain the following result.

Corollary 3.5. Suppose the conditions (H1)-(H2), (H4)-(H5) are satisfied. Then the following system of nonlinear Volterra integral equations has at least one solution $u \in C(I, \mathbb{R}^n)$

$$(3.7) \quad u(t) = \int_0^t a(t-s)f(s, u(s)) ds \quad t \in [0, T],$$

where u is a vector-valued function.

4. An Application. In this section, we present one example which do not aim at generality but indicate how our theorems can be applied to more concrete problems.

Example 4.1. Let c_0 the space of all sequences converging to zero. We know that c_0 is a Banach space with the norm

$$\|x\|_\infty = \sup_{k \in \mathbb{Z}} |x_k|.$$

Consider the following Volterra equation

$$(4.1) \quad u(t) = \int_0^t e^{-\delta(t-s)} f(s, u(s)) ds, \quad t \in I := [0, T],$$

where $0 < \delta < 2$, $0 < T < \frac{1}{2}$ and $f : I \times c_0 \rightarrow c_0$ is given by

$$f(t, x) = \frac{1}{t^2 + \frac{1}{2}} \left(\ln(|x_k| + 1) + \frac{t}{k^2} \right)_{k=1}^\infty, \quad t \in I, \quad x = (x_k)_k \in c_0.$$

We prove the existence of a solution $u \in C(I, c_0)$ for Equation 4.1. To do this, we verify the conditions (H1) to (H5).

(H1).

(a) For every $x \in c_0$ we have that the function

$$t \mapsto f(t, x) = \frac{1}{t^2 + \frac{1}{2}} \left(\ln(|x_k| + 1) + \frac{t}{k^2} \right)_{k=1}^\infty$$

is Lebesgue measurable since it is a continuous function for all $t \geq 0$.

(b) Let $t \in I$ be given. We will see that the function

$$x \mapsto f(t, x)$$

is continuous on c_0 . Before, we recall that the mean value theorem implies that the function $g(s) = \ln(s+1)$ (for $s > 0$) is uniformly continuous on $(0, \infty)$. Now, let (x^n) be a sequence in c_0 such that $x^n \rightarrow x$ in c_0 as $n \rightarrow \infty$. Then

$$\begin{aligned} \sup_k |f(t, x_k^n) - f(t, x_k)| &\leq \frac{1}{t^2 + \frac{1}{2}} \sup_k |\ln(|x_k^n| + 1) - \ln(|x_k| + 1)| \\ &\leq \frac{1}{t^2 + \frac{1}{2}} \sup_k \left| |x_k^n| - |x_k| \right| \leq \frac{1}{t^2 + \frac{1}{2}} \sup_k |x_k^n - x_k| \rightarrow 0 \quad (n \rightarrow \infty) \quad (t \in I). \end{aligned}$$

Hence $\|f(t, x^n) - f(t, x)\|_\infty \rightarrow 0$ as $n \rightarrow \infty$ for all $t \in I$. Thus, we conclude that $f(t, \cdot)$ is continuous for all $t \in I$.

(H2). We define $m : I \rightarrow \mathbb{R}^+$ and $\Phi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ by

$$m(t) = \frac{1}{t^2 + \frac{1}{2}} \quad \text{and} \quad \Phi(t) = t + T.$$

Let $t \in I$ and $x = (x_k)_k$ in c_0 be given. Then we have

$$\begin{aligned} \|f(t, x)\|_\infty &= \left\| \frac{1}{t^2 + \frac{1}{2}} \left(\ln(|x_k| + 1) + \frac{t}{k^2} \right)_k \right\|_\infty \\ &\leq \frac{1}{t^2 + \frac{1}{2}} (\sup_k |x_k| + t) \leq \frac{1}{t^2 + \frac{1}{2}} (\|x\|_\infty + T) = m(t)\Phi(\|x\|_\infty). \end{aligned}$$

Hence (H2) holds.

(H3). We define $H : I \rightarrow \mathbb{R}^+$ and $\phi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ by

$$H(t) = \frac{1}{t^2 + \frac{1}{2}} \quad \text{and} \quad \phi(t) = \ln(t+1).$$

Note that $H \in L^1(I; \mathbb{R}^+)$. Also, we can observe that ϕ is an increasing function and $\lim_{n \rightarrow \infty} \phi^n(t) = 0$ (see [1, Lemma 2.1 and Remark 3.2]). We will prove that for any bounded set $B \subset E$,

$$\gamma(f(t, B)) \leq H(t)\phi(\gamma(B)).$$

Indeed, we recall that the Hausdorff measure of noncompactness γ in the space c_0 can be computed by means of the formula

$$\gamma(B) = \lim_{n \rightarrow \infty} \sup_{x \in B} \|(I - P_n)x\|_\infty,$$

where B is a bounded subset of c_0 and P_n is the projection onto $V_n = \text{span}\{e_1, \dots, e_n\}$ of the first n vectors in the standard basis (see [4]). Next, let $u = (u_k)_k \in B \subset c_0$ and $t \in I$. Fix $n \in \mathbb{N}$. Thus, using the fact that P_n is the identity operator on V_n , we obtain

$$\ln(|u_k| + 1) \leq \ln(\|(I - P_n)(u_k)_k\|_\infty + 1) \quad \text{for all } k > n.$$

Then

$$\begin{aligned} \sup_{u \in B} \|(I - P_n)(\ln(|u_k| + 1)_k)\|_\infty &= \sup_{u \in B} \sup_{k > n} |\ln(|u_k| + 1)| \\ &\leq \sup_{u \in B} \ln(\|(I - P_n)(u_k)_k\|_\infty + 1) \\ &= \ln \left(\sup_{u \in B} \|(I - P_n)(u_k)_k\|_\infty + 1 \right). \end{aligned}$$

Letting $n \rightarrow \infty$ we get

$$\begin{aligned} \lim_{n \rightarrow \infty} \sup_{u \in B} \|(I - P_n)(\ln(|u_k| + 1))_k\|_\infty &= \sup_{u \in B} \sup_{k > n} |\ln(|u_k| + 1)| \\ &\leq \lim_{n \rightarrow \infty} \ln \left(\sup_{u \in B} \|(I - P_n)(u_k)_k\|_\infty + 1 \right) \\ &= \ln \left(\lim_{n \rightarrow \infty} \sup_{u \in B} (\|(I - P_n)(u_k)_k\|_\infty + 1) \right). \end{aligned}$$

On the other hand, for $k > n$ we have that

$$(I - P_n) \left(\frac{t}{k^2} \right)_k = \left(\frac{t}{k^2} \right)_k \leq \left(\frac{t}{n^2}, \frac{t}{n^2}, \dots \right),$$

and consequently

$$\lim_{n \rightarrow \infty} \sup_{u \in B} \left\| (I - P_n) \left(\frac{t}{k^2} \right)_k \right\|_\infty = 0.$$

It follows that

$$\begin{aligned} \gamma(f(t, B)) &= \frac{1}{t^2 + \frac{1}{2}} \lim_{n \rightarrow \infty} \sup_{u \in B} \left\| (I - P_n) \left(\ln(|u_k| + 1) + \frac{t}{k^2} \right)_k \right\|_\infty \\ &\leq \frac{1}{t^2 + \frac{1}{2}} \lim_{n \rightarrow \infty} \sup_{u \in B} \|(I - P_n)(\ln(|u_k| + 1))_k\|_\infty \\ &\leq \frac{1}{t^2 + \frac{1}{2}} \ln \left(\lim_{n \rightarrow \infty} \sup_{u \in B} (\|(I - P_n)(u_k)_k\|_\infty + 1) \right) = H(t)\phi(\gamma(B)). \end{aligned}$$

This proves the claim and hence the condition (H3) is satisfied.

(H4). Is clear from the continuity of $a(t)$.

(H5). We see that there is a solution $p(t) \in C(I, \mathbb{R}^+)$ to the equation

$$(4.2) \quad \Phi(\|p\|_0) \int_0^t a(t-s)m(s) ds \leq p(t), \quad t \in I,$$

Note that

$$(1 * a)(T) = \int_0^T a(s) ds = \int_0^T e^{-\delta s} ds = \frac{1}{\delta} (1 - e^{-\delta T}).$$

Now, we can see (using the mean value theorem) that $\frac{1}{2} \leq \frac{1}{\delta} \ln(\frac{2}{2-\delta})$ for $0 < \delta < 2$. Since $0 < T < \frac{1}{2}$ we get that $0 < T < \frac{1}{\delta} \ln(\frac{2}{2-\delta})$. Then

$$0 < (1 * a)(T) < \frac{1}{2}.$$

Let $p(t) = \lambda$ where

$$(4.3) \quad \lambda \geq \frac{2T(1 * a)(T)}{1 - 2(1 * a)(T)}.$$

Then

$$\begin{aligned} \Phi(\|p\|_0) \int_0^t a(t-s)m(s) ds &= \Phi(\lambda) \int_0^t \frac{e^{-\delta s}}{s^2 + \frac{1}{2}} ds \\ &\leq 2(\lambda + T) \int_0^T e^{-\delta s} ds = 2(\lambda + T)(1 * a)(T) \leq \lambda. \end{aligned}$$

By Theorem 3.1 we obtain the existence of at least one solution to the Volterra equation (4.1).

Remark 4.2. If we consider any kernel $a(t)$ such that (H4) holds and by taking $p(t) = \lambda$ such that the inequality (4.3) holds, then the problem (4.1) always has at least one solution for a suitable value of T , more precisely, for T satisfying

$$0 < (1 * a)(T) < \frac{1}{2}.$$

Remark 4.3. We observe that the Volterra equation (4.1) in the Banach space $E = c_0$ is equivalent to the nonlinear lattice model

$$(4.4) \quad \begin{cases} u_t(t, n) + \delta u(t, n) = f(t, u(t, n)) & t \in [0, T], \quad n \in \mathbb{Z}, \\ u(0, n) = 0. \end{cases}$$

Consequently, the above example says that for the given nonlinear term, and whenever $0 < T < \frac{1}{2}$ and $0 < \delta < 2$ there exist a solution satisfying $|u(t, n)| \rightarrow 0$ as $n \rightarrow \infty$.

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